

Equations are important

$$e^{i\pi} = -1$$

- They are eternally true
- They compress a huge amount of information into a single formula
- The same equation can have many different applications
- Equations lead to algorithms, which lead to new technology

Some famous maths equations

$$a^2 + b^2 = c^2 \quad \text{Pythagoras}$$

$$a^n + b^n = c^n \quad \text{Fermat}$$

$$\left. \begin{aligned} V + F &= E - 2 \\ e^{i\theta} &= \cos(\theta) + i \sin(\theta). \end{aligned} \right\} \text{Euler}$$

Some famous physics equations

$$\mathbf{F}_{12} = \frac{G m_1 m_2 (\mathbf{x}_1 - \mathbf{x}_2)}{\|\mathbf{x}_1 - \mathbf{x}_2\|^3} \cdot \quad \text{Newton}$$

$$i\hbar \frac{\partial \psi}{\partial t} = \left[\frac{-\hbar^2}{2m} \nabla^2 + V(\mathbf{r}, t) \right] \psi \quad \text{Schrödinger}$$

$$\left. \begin{aligned} E &= m c^2 \\ G_{ab} &= 4\pi T_{ab} \end{aligned} \right\} \quad \begin{array}{l} \text{Einstein} \\ \\ \text{Maxwell} \end{array}$$

My Five
Favourite
Equations

$$A x = b$$

$$A x = \lambda x$$

$$\hat{f}(\omega) = \int_{-\infty}^{\infty} e^{-i\omega t} f(t) dt,$$

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i\omega t} \hat{f}(\omega) d\omega$$

$$\frac{Du}{Dt} = -\nabla P + \frac{1}{Re} \nabla^2 u, \quad \nabla \cdot u = 0.$$

$$\frac{dx}{dt} = -\lambda x(t - \tau).$$

Equation one: The Linear Equation

$$Ax = b$$

Most problems end up being this. Shopping, medical imaging, weather forecasting, ..

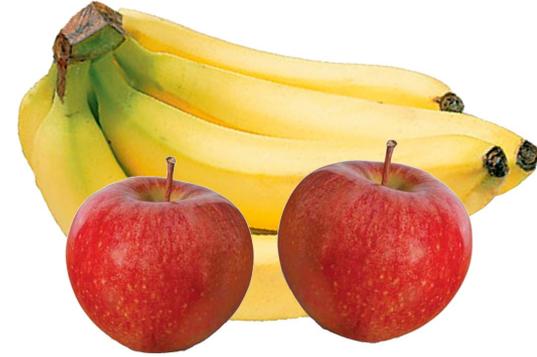
- **b** is known
- **x** is unknown
- **A** is a linear operator linking **x** to **b**

Examples of operators **A**:

Matrix: $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$

Differential: $\frac{d^2 x}{dt^2}$ or even $\frac{\partial^2 x}{\partial y^2} + \frac{\partial^2 x}{\partial z^2}$

Example: Going shopping



Want to buy x apples and y bananas

Apples cost £2 each. Bananas cost £3 each

Budget of £15

Each apple has 4 units of vitamin C, banana has 3 units

Total vitamin C content is 25 units

What values of x and y should we take?

Solution

$$\mathbf{x} = A^{-1}\mathbf{b}$$

$$A^{-1} = \begin{pmatrix} -1/2 & 1/2 \\ 2/3 & -1/3 \end{pmatrix}$$

$$\mathbf{x} = (x, y) \quad \text{where} \quad x = 4 \quad \text{and} \quad y = 3$$

Problem has **two unknowns** and is **easy to solve**

Problem with **many N** unknowns is much harder to solve

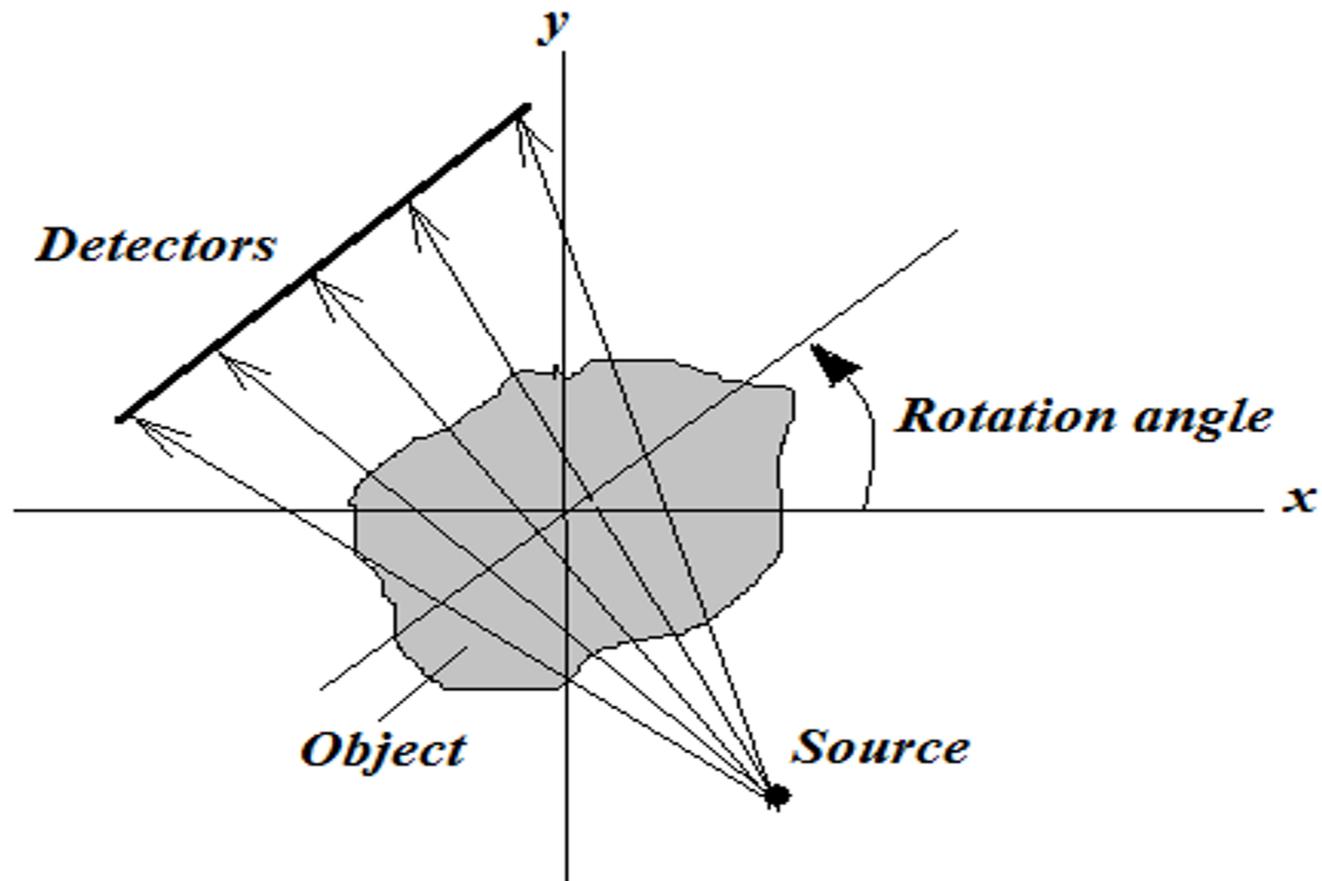
Matters as $Ax = b$ has **vast numbers of applications**

Eg. **medical imaging , weather forecasting, banking,
designing aircraft , building bridges, retail, ...**

$N = 1000\ 000\ 0000$ is not uncommon

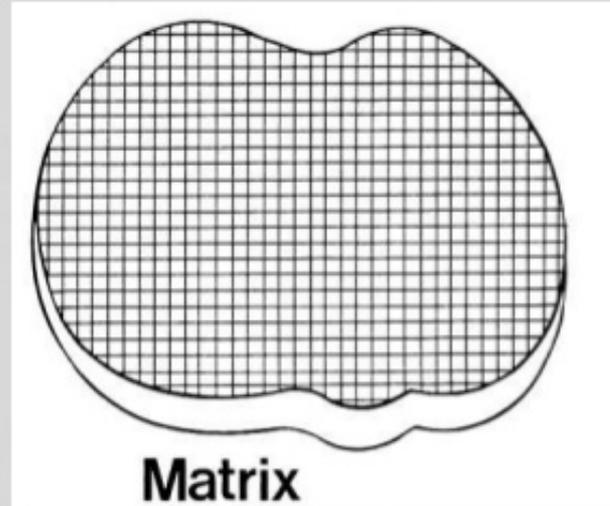
Eg. Medical imaging

Shine many X-Rays through a body



Matrix

- The **image** is represented as a **MATRIX** of numbers.
- **Matrix** :- A two dimensional **array of numbers** arranged in rows and columns.
- Each number represents the value of the image at that location



- x Organ **optical density** at each point (more than..)
- b **Attenuation** of each X-ray
- A **Tomography** matrix

Ill posed as more unknowns than equations

Use a-priori information (Bayesian)



How to solve it?

- Direct method:

Gaussian Elimination

- Iterative method: Successively improve the solution

Conjugate Gradient Method

- Fastest and best (but most complicated)

Multi-grid method

Equation 2: The Matrix Eigenvalue Equation

$$A \mathbf{x} = \lambda \mathbf{x}$$

The equation for sound, WiFi and Google

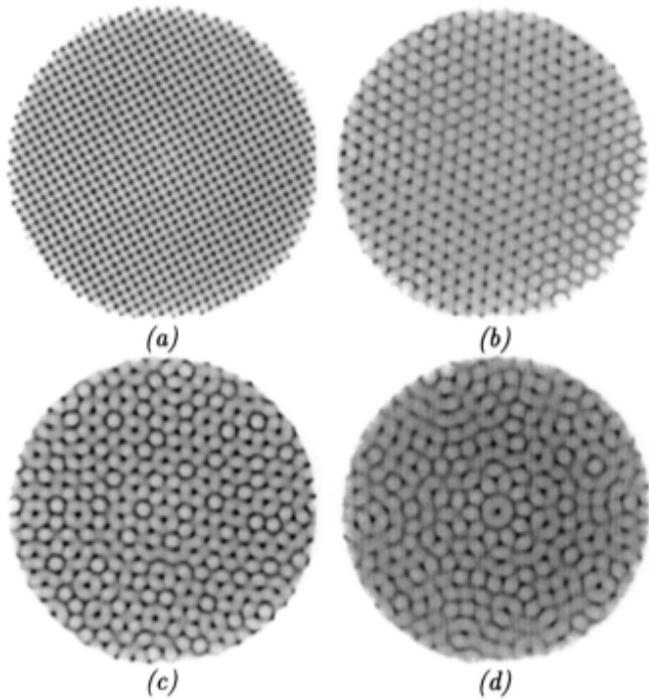


$$\nabla^2 \mathbf{x} = -\omega^2 \mathbf{x}$$

Helmholtz
Equation

ω vibrational frequency

\mathbf{x} vibrational mode



Vibrational waves in a dish

Singing in a football stadium



Example:

$$A = \begin{pmatrix} 2.5 & 0.5 \\ 0.5 & 2.5 \end{pmatrix}$$

$$A \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ 1 \end{pmatrix} \leftarrow \text{Eigenvectors}$$

$$A \begin{pmatrix} 1 \\ -1 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} \leftarrow \text{Eigenvectors}$$

Eigenvalues

$$\lambda = 3 \quad \text{or} \quad \lambda = 2$$

If A is an $N \times N$ matrix then there are N solutions.

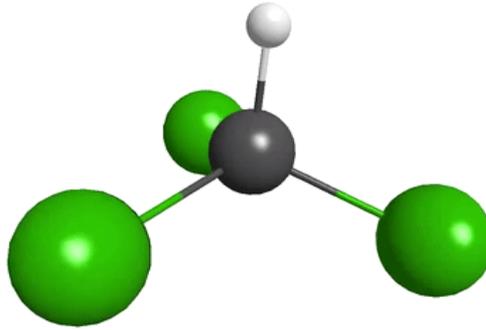
These satisfy

$$\det(A - \lambda I) = 0$$

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

$$\lambda^2 - (a + d)\lambda + ad - bc = 0$$

Vibration in engineering, chemistry, physics



Acoustics, Maxwell, Electromagnetic theory, WiFi

$$\nabla^2 \mathbf{x} = -\omega^2 \mathbf{x}$$

Quantum theory

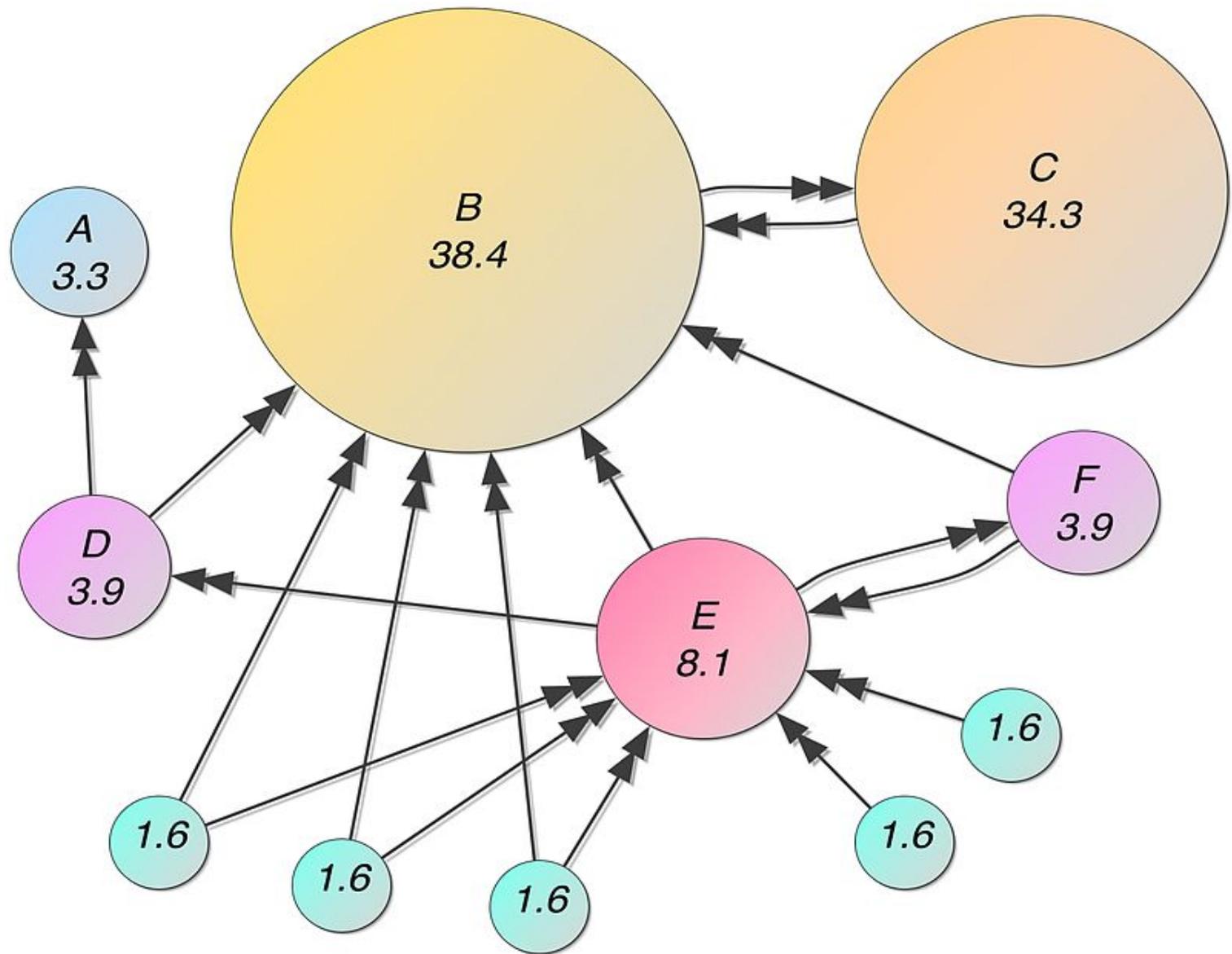
$$i\hbar \frac{\partial \psi}{\partial t} = \left[\frac{-\hbar^2}{2m} \nabla^2 + V(\mathbf{r}, t) \right] \psi$$

PageRank Algorithm



- The i th webpage gets rank R_i
- This page will be pointed to by m other pages.
- These each have ranks R_{ij} and point to N_{ij} other pages
- The ranks satisfy (Damping $d = 0.85$)

$$R_i = \frac{(1 - d)}{N} + d \left(\frac{R_{i1}}{N_{i1}} + \frac{R_{i2}}{N_{i2}} + \dots + \frac{R_{im}}{N_{im}} \right).$$



Wikipedia

Posed as a matrix eigenvalue equation

$$M R = R$$

M: Augmented adjacency matrix **HUGE**

Eigenvalue of one. Need to find **eigenvector R**

Use iteration $R^{n+1} = M R^n$

Works fast and is the basis of Google

Equation 3: The Fourier Transform

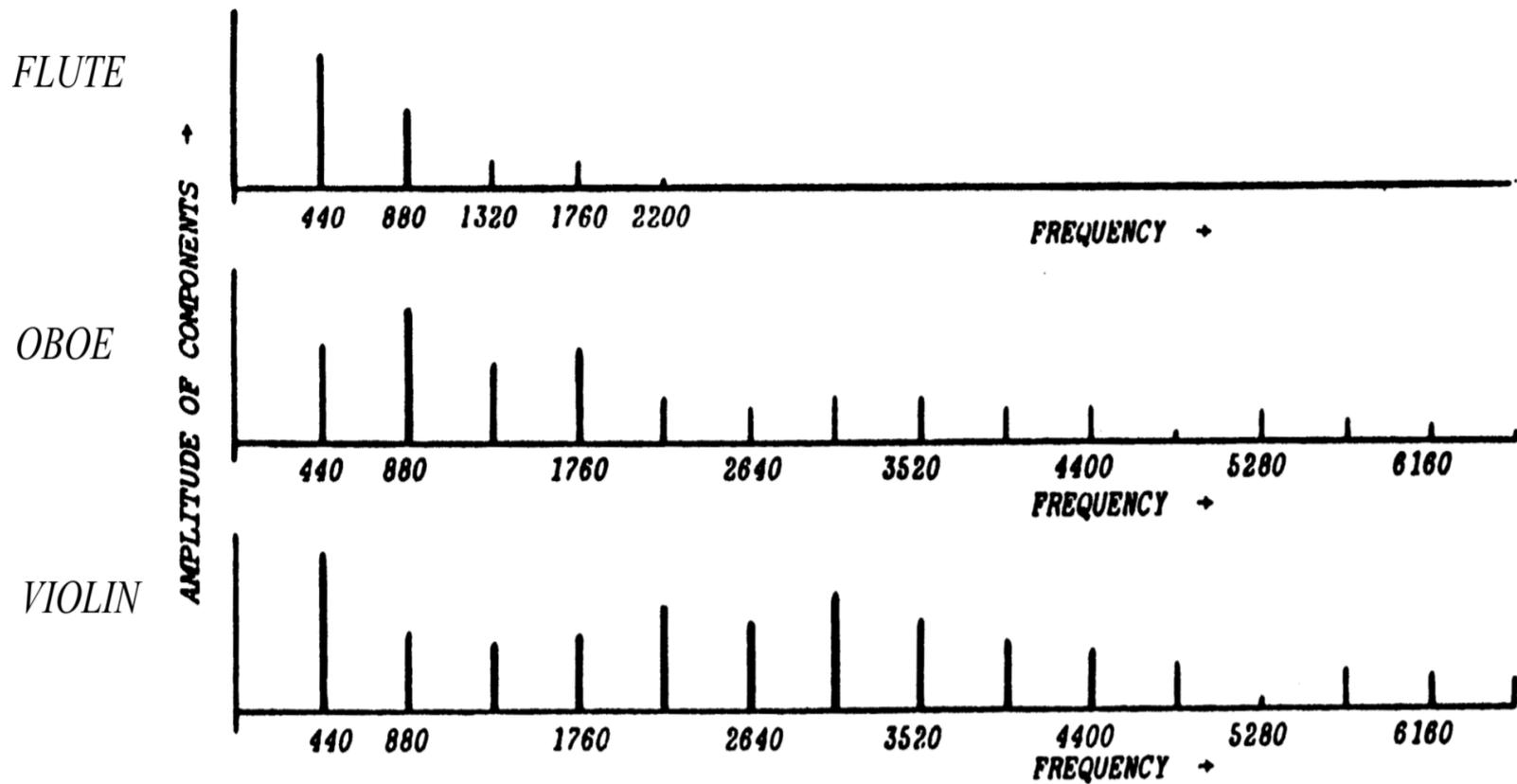
$$\hat{f}(\omega) = \int_{-\infty}^{\infty} e^{-i\omega t} f(t) dt,$$

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i\omega t} \hat{f}(\omega) d\omega$$

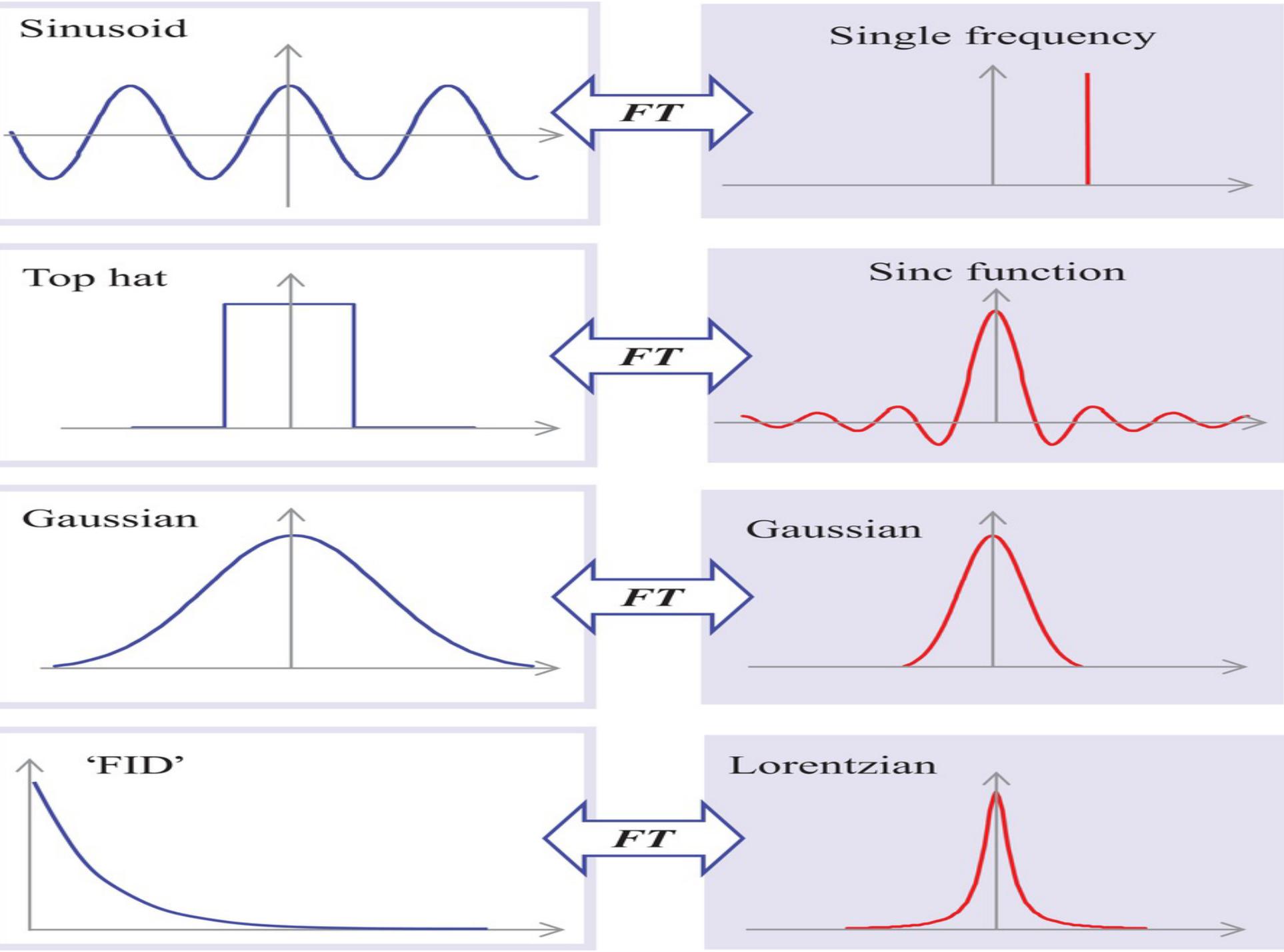
Decomposing a function into its constituent waves



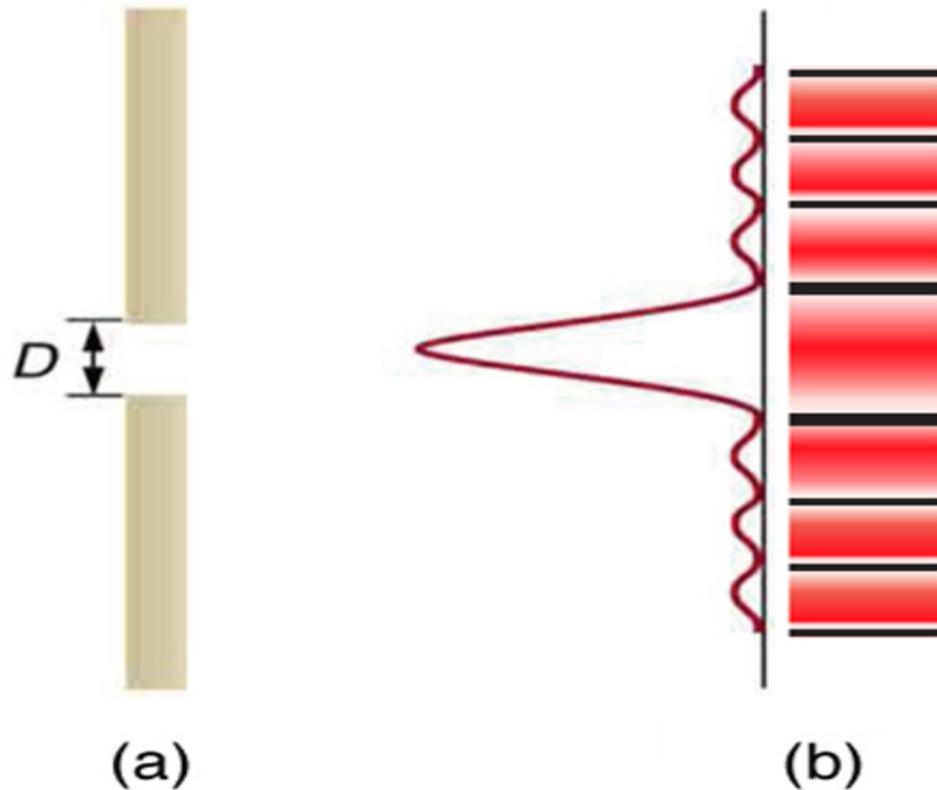
Look at the different harmonics of the notes



Find these harmonics by using the Fourier Transform

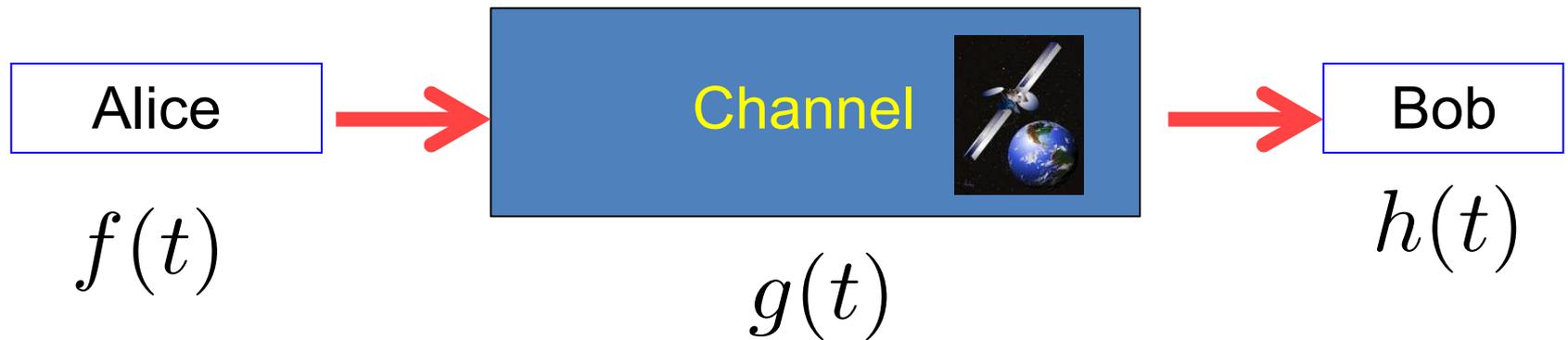


Diffraction of light through a slit



Fourier Transform is THE essential tool in optics, telecommunications, image processing, spectral analysis, acoustics,

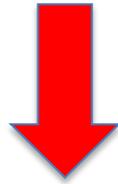
Want to communicate over a channel



$$h(t) = \int_{-\infty}^{\infty} f(t - \tau) g(\tau) d\tau.$$

Convolution

$$h = f * g$$



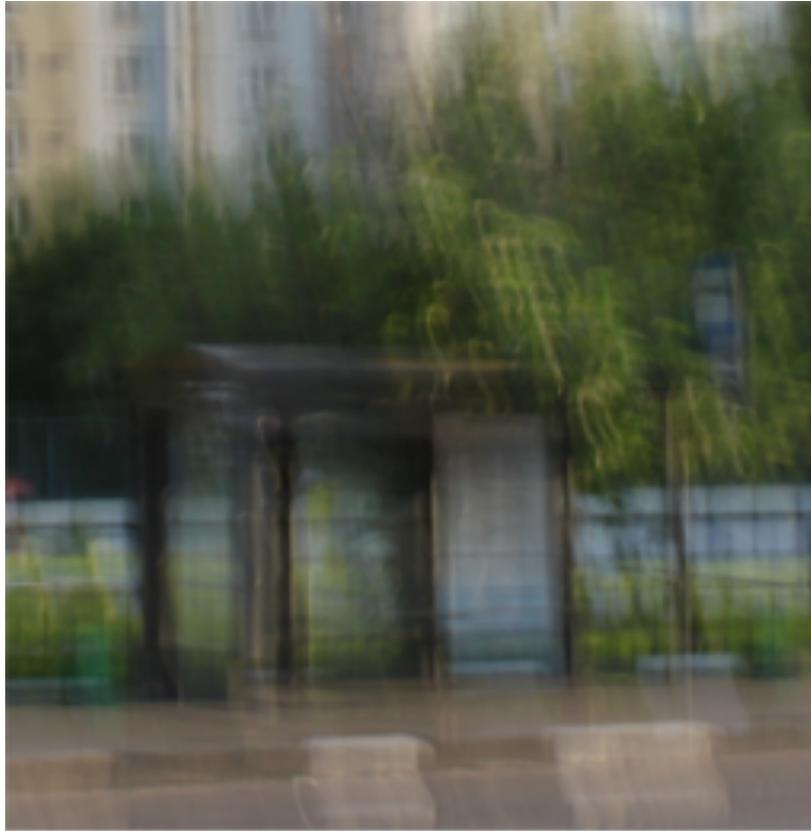
$$\hat{h} = \hat{f} \hat{g}.$$

Convolution
theorem

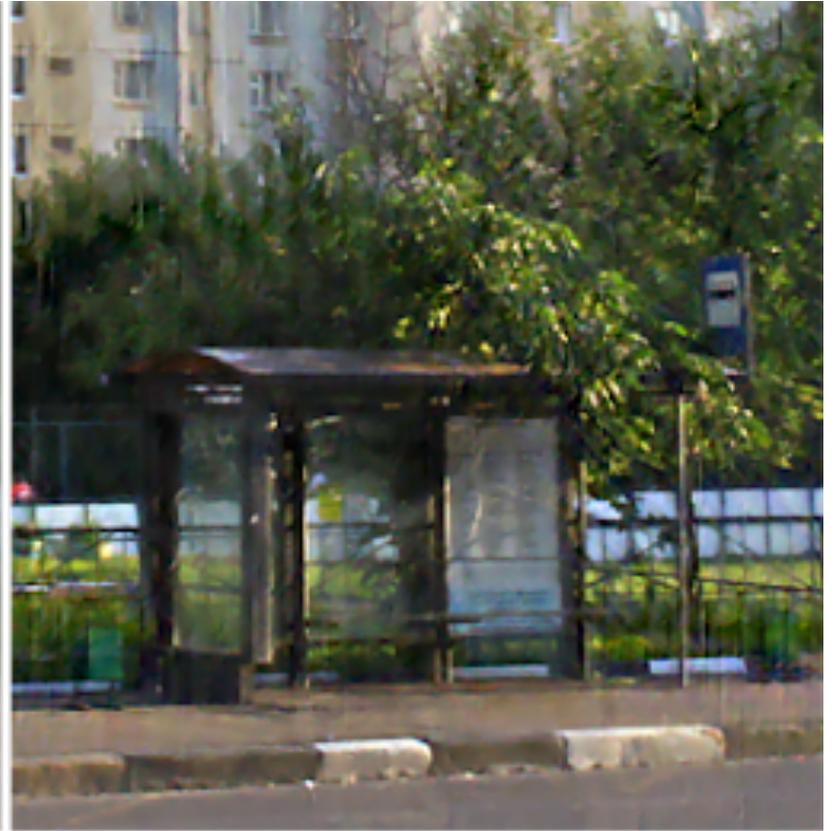


$$\hat{f} = \frac{\hat{h}}{\hat{g}}$$

Deblurring

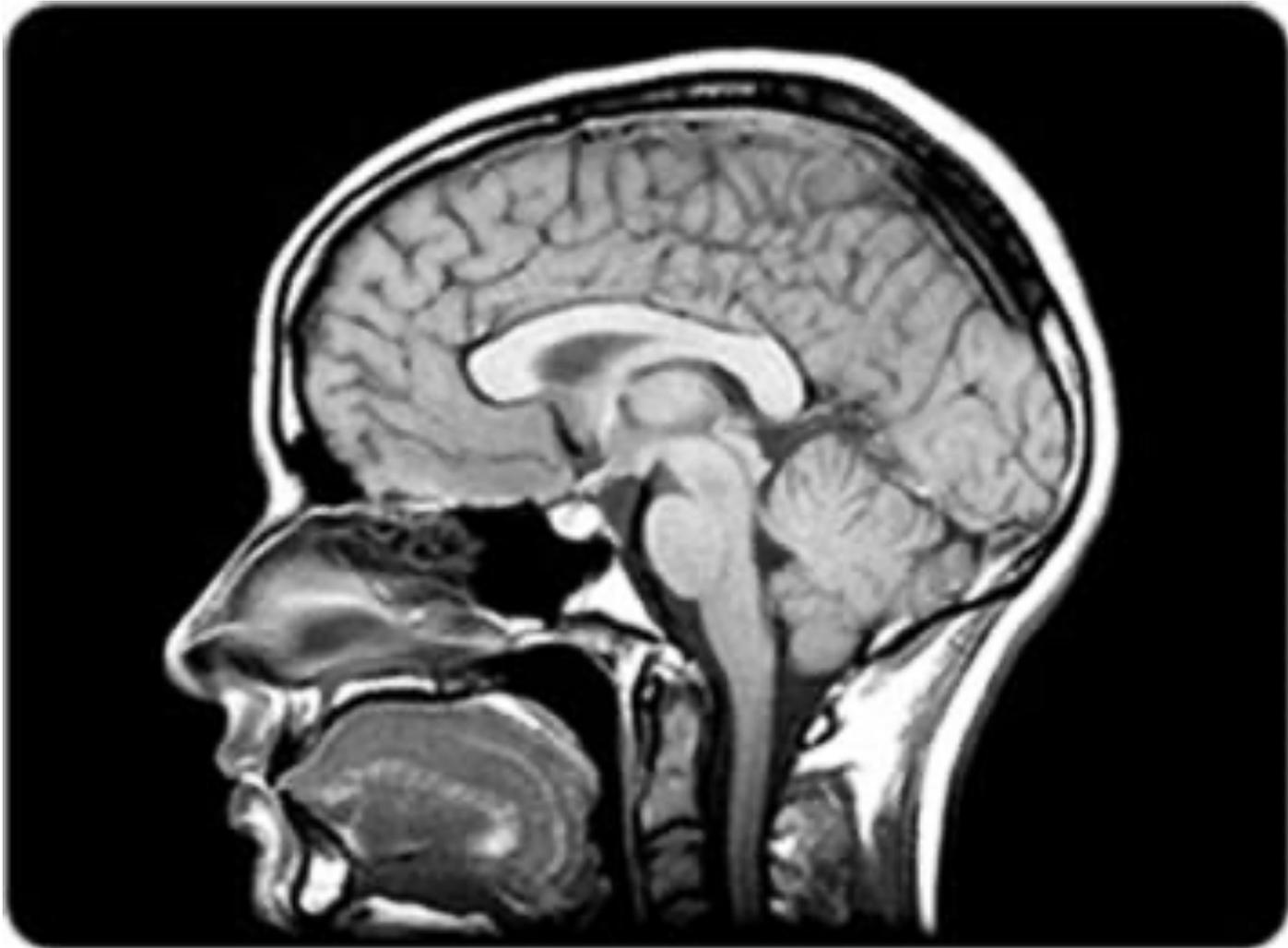


Before

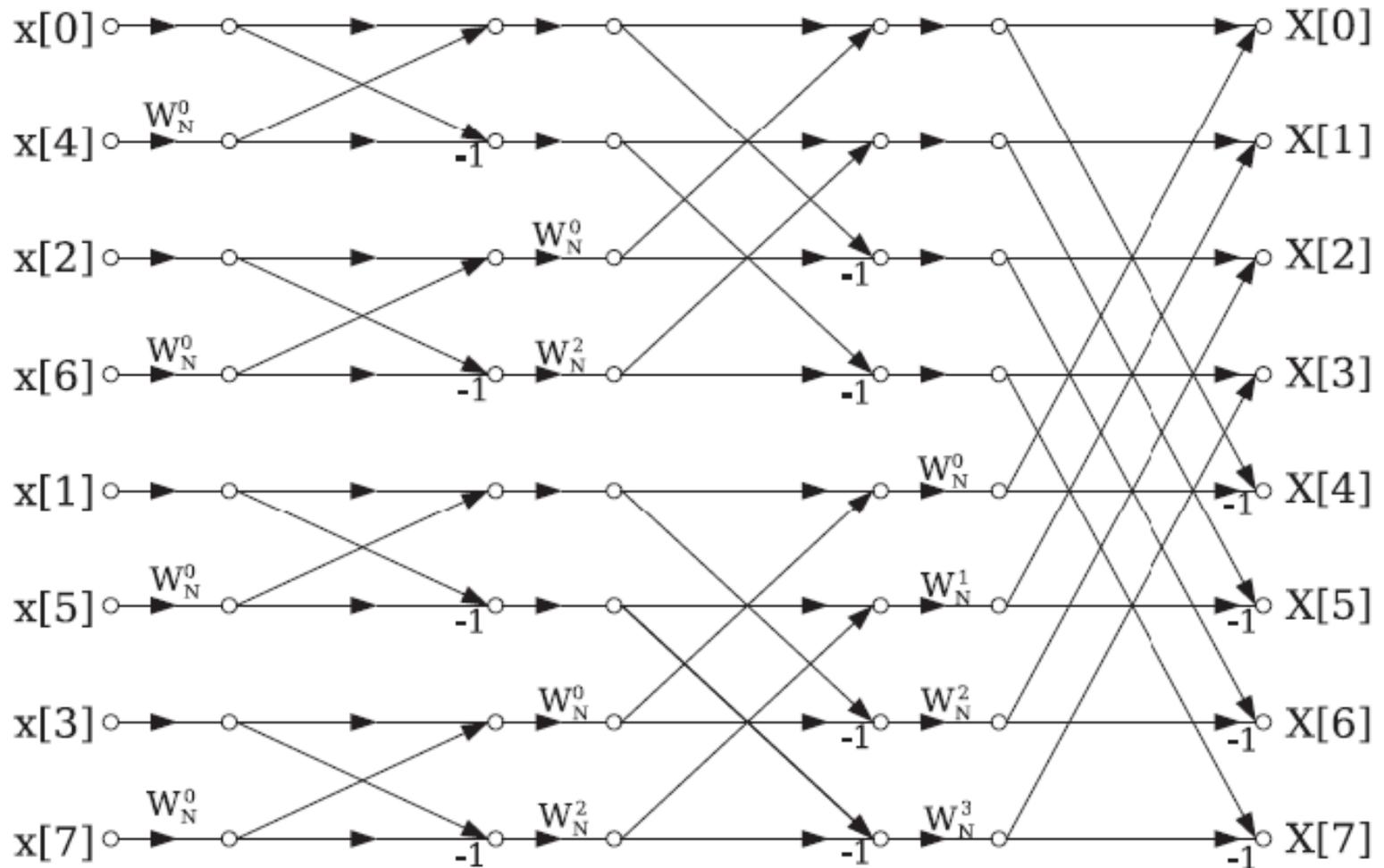


After

MRI Imaging



Evaluate using the FFT Algorithm (1965)



THE BEATLES

**WE CAN WORK IT OUT
DAY TRIPPER**

1965 



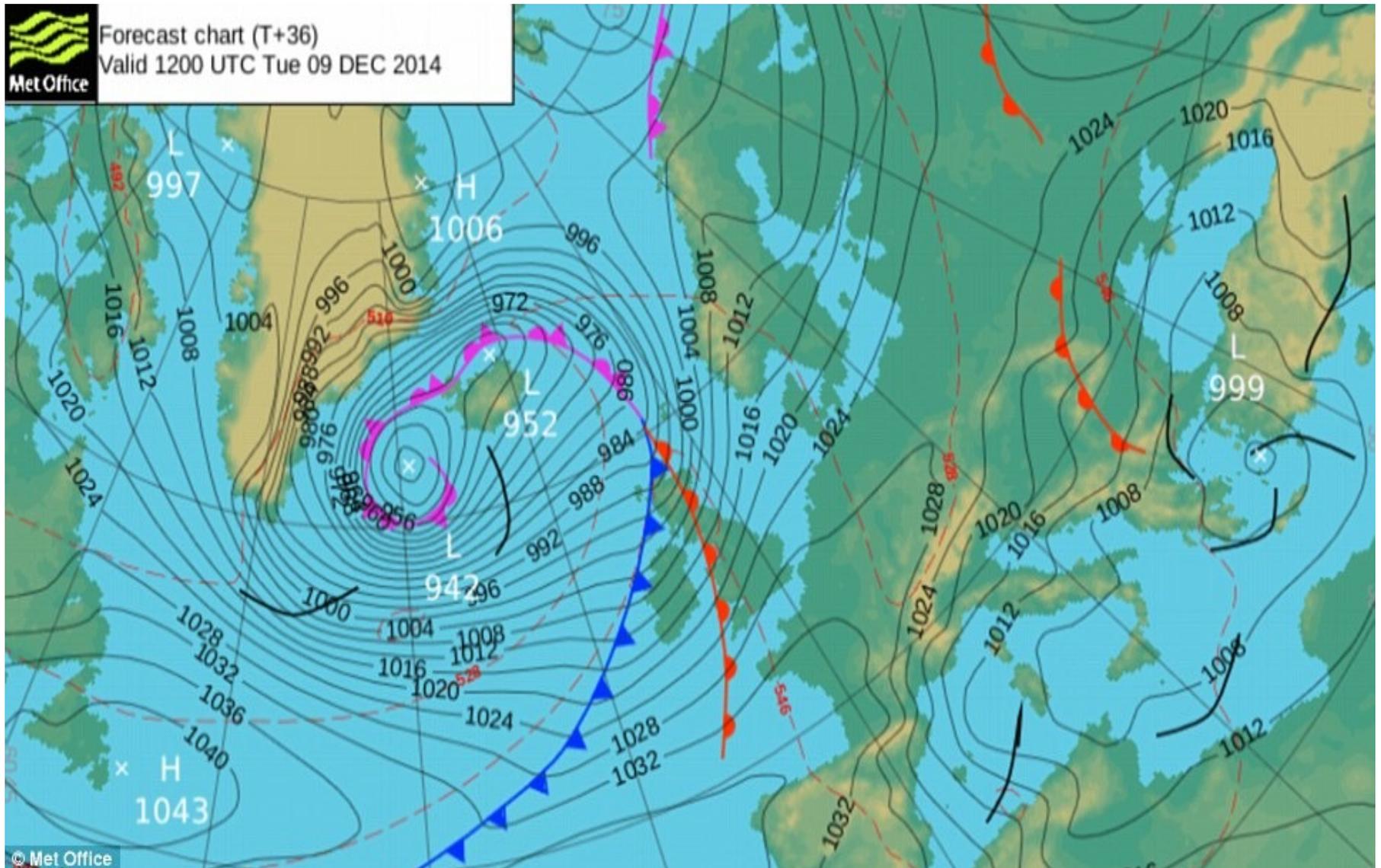
Equation 4: The Navier-Stokes Equations

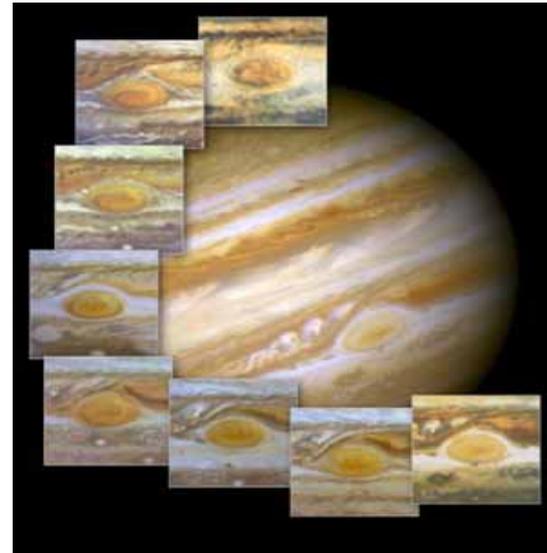
$$\frac{D\mathbf{u}}{Dt} + 2\mathbf{f} \times \mathbf{u} = -\frac{1}{\rho}\nabla P + \frac{1}{Re}\nabla^2\mathbf{u} - g\mathbf{k},$$

$$\frac{\partial\rho}{\partial t} + \nabla\cdot(\rho\mathbf{u}) = 0.$$

The equations of the weather

The equations for weather and climate

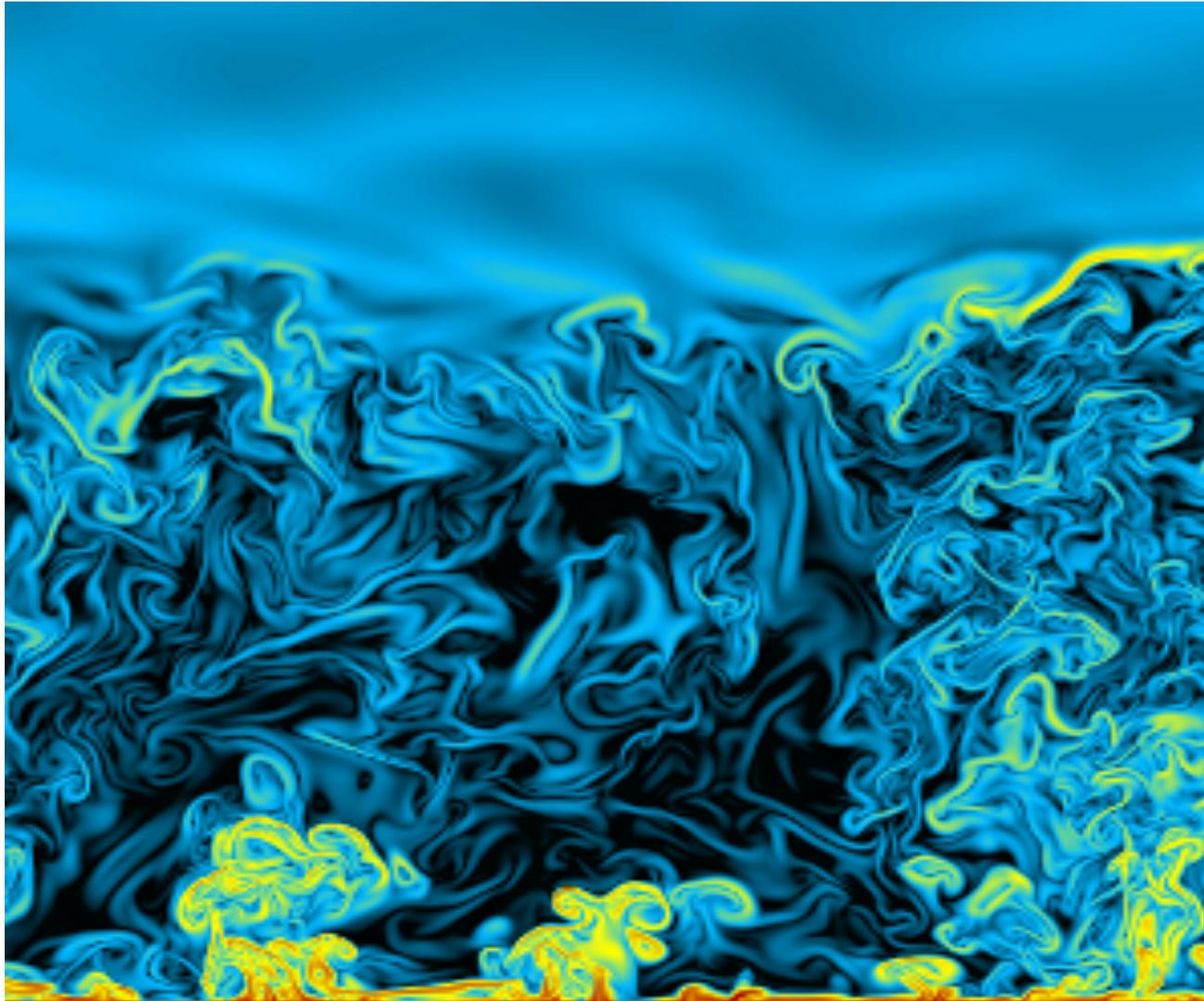




The Navier-Stokes equations:

- Are extremely important
- Are VERY hard to solve, even on a super computer
- Have very complex, and even chaotic solutions
- We don't even know if they have regular solutions at all!

Turbulence



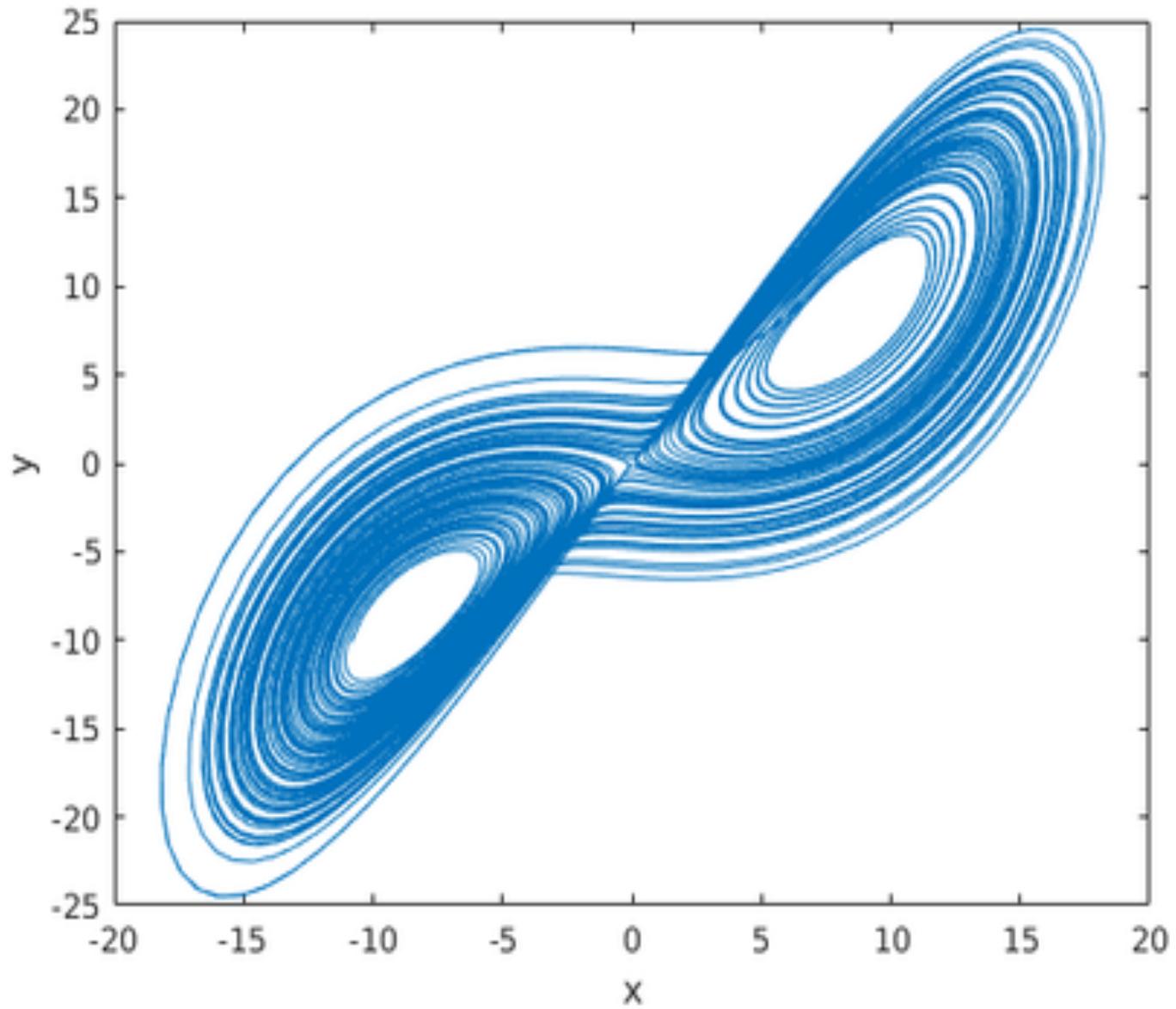
The Lorenz Equations for chaos

$$\frac{dx}{dt} = \sigma(y - x),$$

$$\frac{dy}{dt} = x(\rho - z) - y,$$

$$\frac{dz}{dt} = xy - \beta z.$$

Chaotic strange attractor



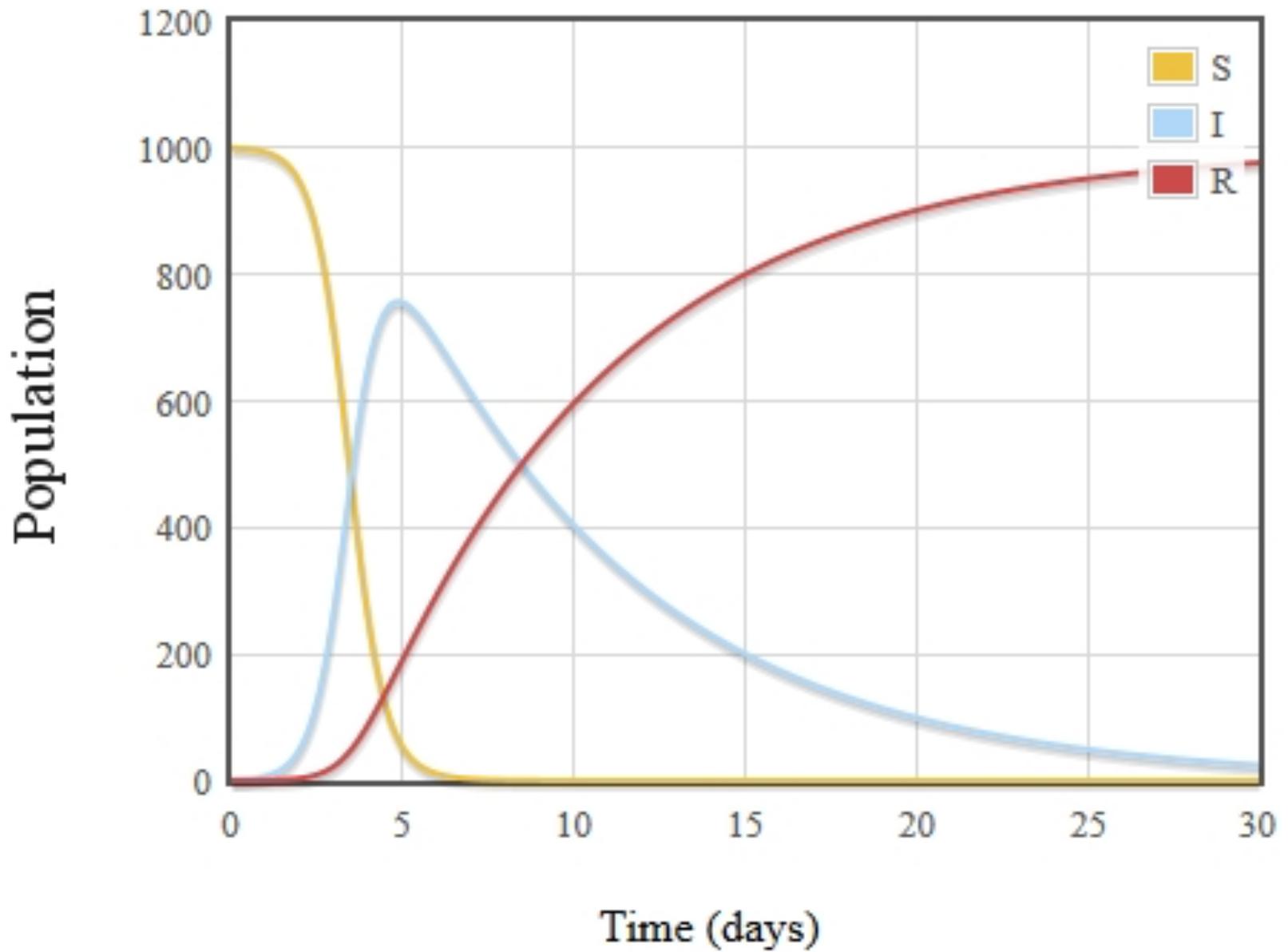
The SIR equations for an epidemic

$$\frac{dS}{dt} = -\frac{\beta IS}{N},$$

$$\frac{dI}{dt} = \frac{\beta IS}{N} - \gamma I,$$

$$\frac{dR}{dt} = \gamma I.$$

Predictions of the SIR model



Equation 5: The Shower Equation

$$\frac{dx}{dt} = -\lambda x(t - \tau).$$

This equation explains how we can control things



Can you control
a shower if
there is a delay
of τ
between the
control and its
effect?

$$\frac{dx}{dt} = -\lambda x(t - \tau).$$

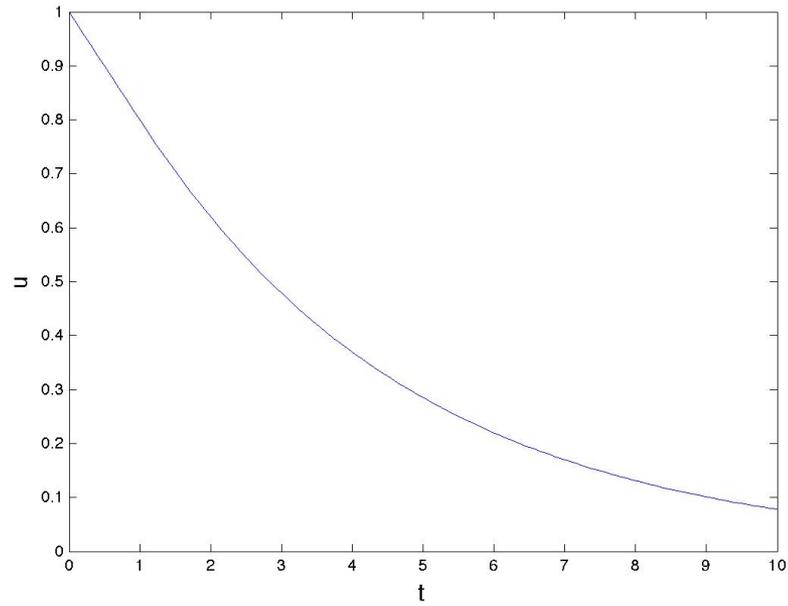
$$x(t) = e^{\alpha t}$$

$$\alpha e^{\alpha t} = -\lambda e^{\alpha(t-\tau)} = -\lambda e^{\alpha t} e^{-\alpha \tau}$$

$$\alpha = -\lambda e^{-\alpha \tau}.$$

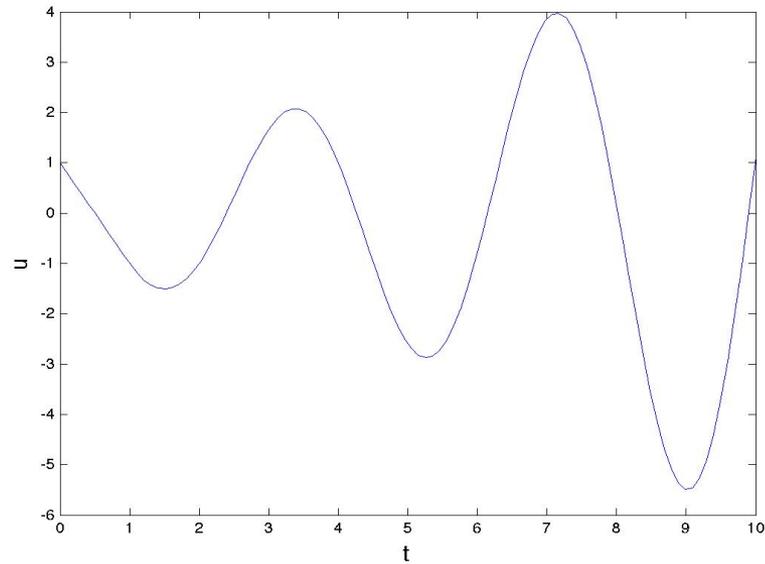
Stable control only if the real part of alpha is negative

$$\lambda\tau < \frac{\pi}{2}$$



Controlled

$$\lambda\tau > \frac{\pi}{2}$$

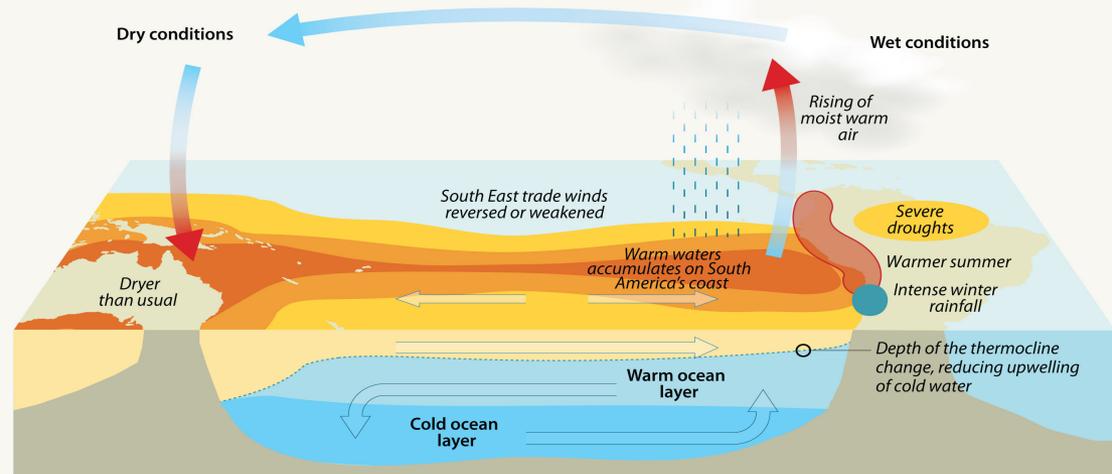


Uncontrolled

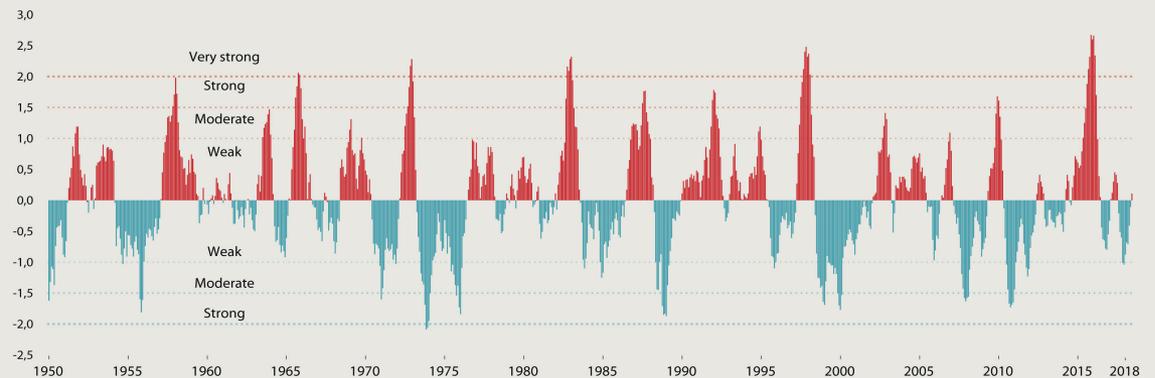
The El Niño Southern Oscillation ENSO

Delay leads to hard to predict behaviour

The effect of El Niño on weather in the Andes



Cold and warm episodes
Oceanic Niño Index



Most things we try to control have a **delay**

This can make it very **hard to control them**

The shower problem is a good example

**So is the impact of responses to the COVID-19
emergency**

There has never been a time
when an understanding of
mathematics is more
important to our lives